Pneumatic • 2-Finger Parallel Gripper • Universal Gripper



Sizes 40 ... 380



Weight 0.08 kg ... 39.5 kg



Gripping force 123 N ... 21150 N



Stroke per finger 2 mm ... 45 mm



Workpiece weight 0.62 kg ... 80.5 kg







Pneumatic • 2-Finger Parallel Gripper • Universal Gripper

Universal Gripper

Universal 2-finger parallel gripper with large gripping force and high maximum moments thanks to multi-tooth guidance.

Field of application

Ideal standard solution for numerous fields of application. For universal use in clean to slightly dirty environments. Special versions available for dirty environments.

Your advantages and benefits

Robust multi-tooth guidance for precise handling

High maximum moments possible suitable for using long gripper fingers

Drive concept oval piston for maximum gripping forces

Mounting from two sides in three screw directions possible for universal and flexible gripper assembly

Air supply via hose-free direct connection or screw connections for universal and flexible gripper assembly

Comprehensive sensor accessory program for versatile interrogation possibilities and control of stroke position

Compact dimensions for minimal interfering contours in handling

Manifold options

for perfect adaption to your case of application (dust protection, high temperature, anti-corrosion and many more)





General note to the series

Principle of function Wedge-hook kinematics

Housing material Aluminum

Base jaw material Steel

Actuation

pneumatic, with filtered compressed air (10 microns): dry, lubricated or non-lubricated Pressure medium: Required quality class of compressed air according to DIN ISO 8573-1: 6 4 4

Warranty

36 months (details, general terms and conditions and operation manuals can be downloaded under www.schunk.com)

Scope of delivery

Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly and operating manual with manufacturer's declaration

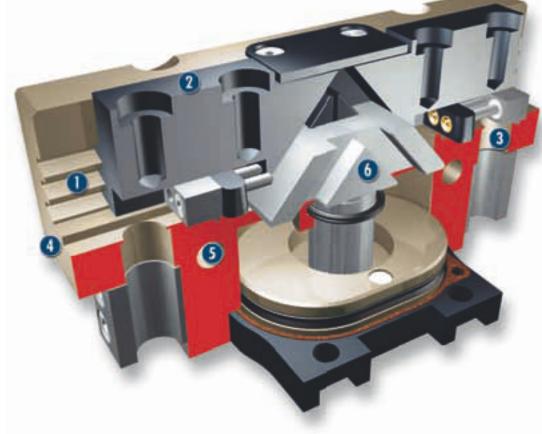
Gripping force maintenance device

with either mechanical gripping force maintenance or SDV-P pressure maintenance valve



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Sectional diagram



0

2

Multiple-tooth guidance

high-loadable base jaw guidance with minimum play for long fingers

Base jaw

for the connection of workpiece-specific gripper fingers



Sensor system

Brackets for proximity switches and adjustable control cams in the housing

🕘 Housing

weight-optimized through application of hardanodized, high-strength aluminum alloy



Centering and mounting possibilities for universal assembly of the gripper



Wedge-hook design

for high power transmission and centric gripping

Functional description

The oval piston is moved up or down by means of compressed air. Through its angled active surfaces, the wedge hook transforms this movement into the lateral, synchronous gripping movement of both base jaws.

Options and special information

Dust-protection version

Absolutely sealed, increased degree of protection against the ingress of materials, for use in dusty environments

Anti-corrosion version for use in corrosion-inducing atmospheres

High-temperature version for use in hot environments

Force intensified version if higher gripping forces are required

Precision version for a higher accuracy



Compensation unit

Pneumatic • 2-Finger Parallel Gripper • Universal Gripper

Universal intermediate

jaw

Accessories

Accessories from SCHUNK the suitable supplement for maximum functionality, reliability and performance of all automation modules.

Protection cover



Quick-change Jaw System



Pressure maintenance valve





Force measuring jaws



Analog position sensor



Flexible Position Sensor



Tor the exact size of the required accessories, availability of this size and the designation and ID, please refer to the additional views at the end of the size in question. You will find more detailed information on our accessory range in the "Accessories" catalog section.

General note to the series

Gripping force

is the arithmetic total of the gripping force applied to each finger at distance P (see illustration) measured from the upper edge of the gripper.

Finger length

The finger length is measured from the upper edge of the gripper housing in the direction of the main axis.

Repeat accuracy

is defined as the spread of the limit position after 100 consecutive strokes.

Workpiece weight

The recommended workpiece weight is calculated for a force-type connection with a coefficient of friction of 0.1 and a safety factor of 2 against slippage of the workpiece on acceleration due to gravity g. Considerably heavier workpiece weights are permitted with form-fit gripping.

Closing and opening times

Closing and opening times are purely the times that the base jaws or fingers are in motion. Valve switching times, hose filling times or PLC reaction times are not included in the above times and must be taken into consideration when determining cycle times.



Fittings

Sensor system

Sensor cables

Sensor Distributor



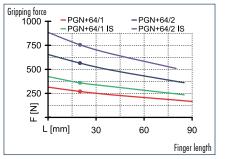


SCHUNK

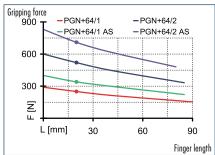
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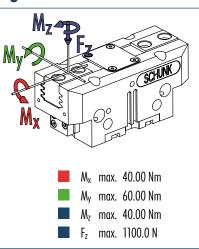
Gripping force, I.D. gripping



Gripping force, O.D. gripping



Finger load



The indicated moments and forces are static values, apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may be reduced.

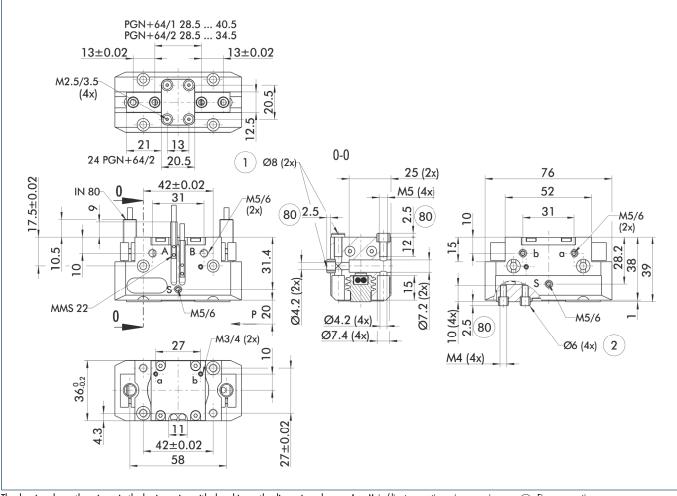
Technical data

Description	PGN-plus 64-1	PGN-plus 64-2	PGN-plus 64-1-AS	PGN-plus 64-2-AS	PGN-plus 64-1-IS	PGN-plus 64-2-IS
ID	0371090	0371091	0371092	0371093	0371094	0371095
Stroke per finger [mm]	6	3	6	3	6	3
Closing force [N]	250	520	340	710		
Opening force [N]	270	565			360	755
Min. spring force [N]			90	190	90	190
Weight [kg]	0.28	0.28	0.37	0.37	0.37	0.37
Recommended workpiece weight [kg]	1.25	2.6	1.25	2.6	1.25	2.6
Air consumption per double stroke [cm ³]	9	9	48	48	48	48
Min./max. operating pressure [bar]	2.5/8	2.5/8	4/6.5	4/6.5	4/6.5	4/6.5
Nominal operating pressure [bar]	6	6	6	6	6	6
Closing/opening time [s]	0.03/0.03	0.03/0.03	0.02/0.04	0.02/0.04	0.04/0.02	0.04/0.02
Max. permitted finger length [mm]	90	85	85	80	85	80
Max. permitted weight per finger [kg]	0.35	0.35	0.35	0.35	0.35	0.35
IP class	40	40	40	40	40	40
Min./max. ambient temperature [°C]	-10/90	-10/90	-10/90	-10/90	-10/90	-10/90
Repeat accuracy [mm]	0.01	0.01	0.01	0.01	0.01	0.01
Cleanroom class	5	5	5	5	5	5
ISO-classification 14644-1		J	J	J	J	J
OPTIONS and their characteristics						
Dust-protection version	37371090	37371091	37371092	37371093	37371094	37371095
IP class	64	64	64	64	64	64
Weight [kg]	0.35	0.35	0.44	0.44	0.44	0.44
Anti-corrosion version	38371090	38371091	38371092	38371093	38371094	38371095
High-temperature version	39371090	39371091	39371092	39371093	39371094	39371095
Min./max. ambient temperature [°C]	-10/130	-10/130	-10/130	-10/130	-10/130	-10/130
Force intensified version	PGN-plus 64-1-KVZ	PGN-plus 64-2-KVZ	PGN-plus 64-1- AS-KVZ		PGN-plus 64-1- IS-KVZ	
ID	0372090	0372091	0372092		0372093	
Closing force [N]	450	520	540			
Opening force [N]	485	1015			575	
Weight [kg]	0.35	0.35	0.43		0.43	
Maximum pressure [bar]	6	6	6		6	
Max. permitted finger length [mm]	80	64	64		64	
Precision version	0371122	0371172	0371422	0371437		



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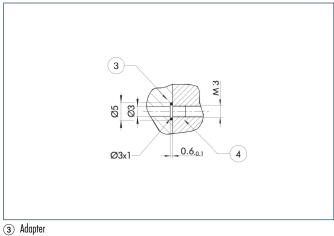
Main view



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

- (1) The SDV-P pressure maintenance valve can also be used for I.D. or O.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see "Accessories" catalog section).
- A, a Main/direct connection, gripper opening
- B, b Main/direct connection, gripper closing S
 - Air purge connection, or deaeration bore
 - Gripper connection
- (2) Finger connection
- Depth of the centering sleeve hole in the 80 matching part
- (1)

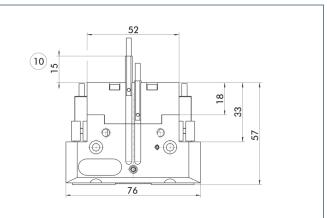
Hose-free direct connection



⁽⁴⁾ Gripper

The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

AS/IS gripping force maintenance device



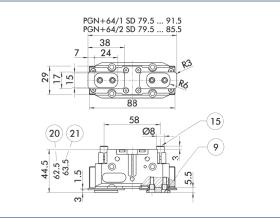
⁽¹⁰⁾ Projection applies only for AS version

The mechanical gripping force maintenance device ensures a minimum gripping force even in case of pressure drop. This acts as closing force in the AS version, and as opening force in the IS version. In addition, the gripping force maintenance device can also be used for increasing the gripping force or for single-acting gripping.



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Dust-protection version

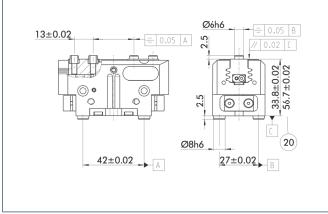


(20) For AS / IS version For mounting screw connection diagram, see 9 basic version (21) Applies for KVZ version

Sealing bolt (15)

The "dust-protection" option increases the degree of protection against penetrating substances. The screw connection diagram shifts by the height of the intermediate jaw. The finger length is still measured from the upper edge of the gripper housing.

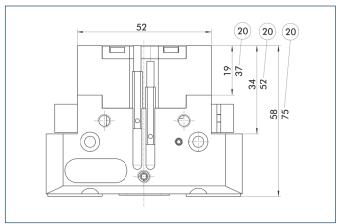
Precision version



20 For AS / IS version

The indicated tolerances just refer to the types of precision versions shown in the chart of technical specifications. All other types of precision versions are available on request.

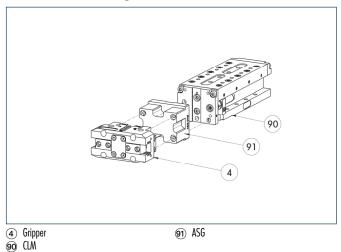
Force intensified version



(20) For AS / IS version

The KVZ cylinder increases the gripping forces during opening and closing. A second, in series-connected piston also increases the force on the wedge hook. The full gripping force shown in the data table is sometimes only reached after a few hundred gripping cycles. Please consider that grippers which are equipped with a gripping force maintenance device (AS / IS) are higher.

Modular Assembly Automation

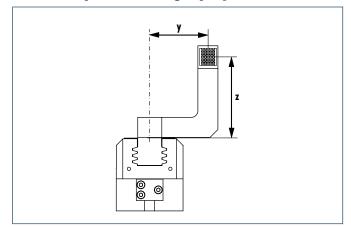


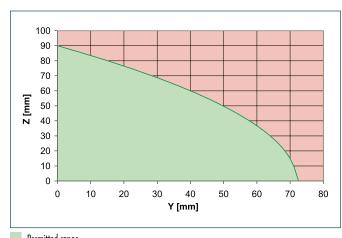
This gripper can be combined with the standard linear modules LM, KLM, CLM and ELM of the GEMOTEC modular system. For more information see our main catalog "Modular Assembly Automation".



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Maximum permitted finger projection



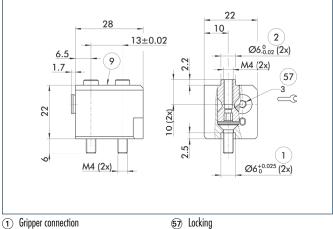


Permitted range

Inadmissible range

The curve applies to the basic version (stroke -1). For other versions, the curve will be parallel but offset in line with the max. permitted finger length.

Quick-change Jaw System



(2) Finger connection

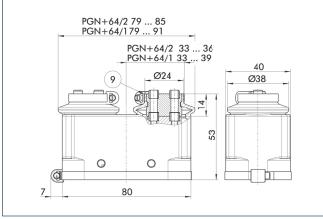
 For mounting screw connection diagram, see basic version

The BSWS quick-change jaw system enables top jaws to be changed on the gripper manually and rapidly. An adapter (BSWS-A) and a base (BSWS-B) are required for each gripper jaw.

For a reverse assembly without height set-up, one adapter (BSWS-A) and a kit (BSWS-U) per gripper jaw are required. Another effect of the BSWS-U is, that there are no disturbing fastening bores in the finger contour.

Description	ID
Quick-change Jaw System adapter	ſ
BSWS-A 64	0303022
Quick-change Jaw System base	
BSWS-B 64	0303023
Quick-change Jaw System reverse	d
BSWS-U 64	0303041

Protection cover



(9) For mounting screw connection diagram, see basic version

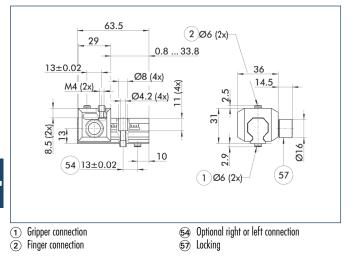
The HUE protective cover completely protects the gripper against external influences up to IP65 if an additional sealing of the cover bottom is provided as part of the application. The mounting diagram shifts by the height of the intermediate jaw.

Description	ID	Cleanroom class ISO-classification 14644-1
Protection cover		
HUE PGN-plus 64	0371480	2



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Universal intermediate jaw

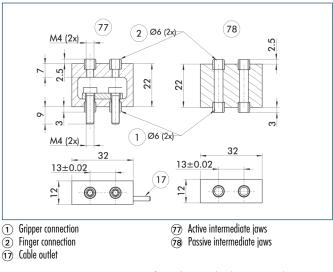


The universal intermediate jaw allows fast tool-free and reliable plugging and shifting of top jaws at the gripper.

Description	ID	Grid dimension
Universal intermediate jaw		
UZB 64	0300042	1.5 mm

The slide UZB-S can be removed completely and has to be ordered separately. Moreover, it allows a fast jaw change.

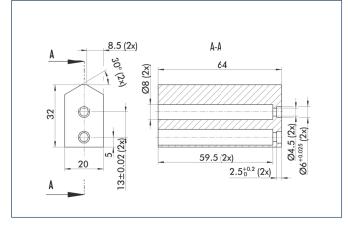
Force measuring jaws



Force measuring jaws measure gripping forces, but can also determine workpiece weights or dimensional deviations. There are active and passive intermediate jaws (FMS-ZBA or FMS-ZBP). At least one active force measuring jaw is required per gripper, the rest can be passive. For each active jaw, a FMS-A1 control unit and a FMS-A connection cable are required.

Description	ID
Active intermediate jaws	
FMS-ZBA 64	0301832
Passive intermediate jaws	
FMS-ZBP 64	0301833
Electronic Processor	
FMS-A1	0301810
Connection cables	
FMS-AK0200	0301820
FMS-AK0500	0301821
FMS-AK1000	0301822
FMS-AK2000	0301823

Finger blanks



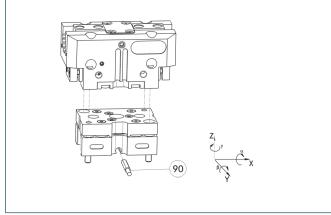
Finger blanks for customized subsequent machining

Description	ID	Material	Scope of delivery
Finger blanks			
ABR-plus 64	0300010	Aluminum	1
SBR-plus 64	0300020	16 MnCr 5	1



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Tolerance compensation unit

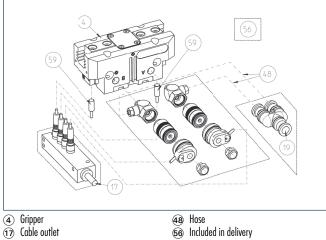


(90) Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details see catalog "Robot Accessories".

Description	ID	Locking	Deflection
Compensation unit			
TCU-064-3-MV-P	0324774	Yes	±3°/±1°/±2°
TCU-064-3-0V-P	0324775	No	±3°/±1°/±2°

Attachment valves

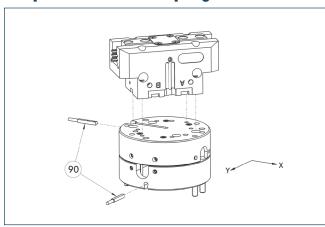


- (19) Air connection
- 59 Monitoring "gripping"

For each gripper one attachment valve ABV is required, optional with distributor for sensors and valves. Attachment valves increase the efficiency, reduce the installation work and air consumption and simplify air supply. For details please refer to the "Accessories" catalog section.

Description	ID	
Attachment valves		
ABV-MV15-M5	0303323	
ABV-MV15-M5-V2-M8	0303386	
ABV-MV15-M5-V4-M8	0303356	
ABV-MV15-M5-V8-M8	0303357	

Compensation unit with spring reset

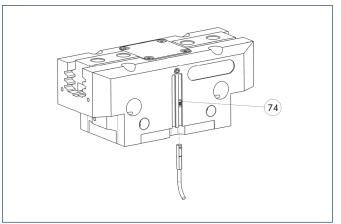


(90) Monitoring

Grippers can be directly mounted without using an adapter plate. For details see our catalog "Robot Accessories".

Description	ID	Compensation travel	Reset force
Compensation unit			
AGE-F-XY-063-1	0324940	±4 mm	9 N
AGE-F-XY-063-2	0324941	±4 mm	10 N
AGE-F-XY-063-3	0324942	±4 mm	19.3 N

Programmable magnetic switch



(74) Stop for MMS-P

Position monitoring with two programmable positions per sensor. The end position monitoring is mounted in the C-slot.

Description	ID	Recommended product
Programmable magnetic switch		
MMS-P 22-S-M8-PNP	0301370	•
MMSK-P 22-S-PNP	0301371	
Connection cables		
KA BG08-L 4P-0500	0307767	
KA BG08-L 4P-1000	0307768	
KA BW08-L 4P-0500	0307765	
KA BW08-L 4P-1000	0307766	
Sensor Distributor		
V2-M8-4P-2XM8-3P	0301380	

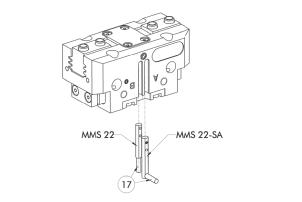
(1) Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

() Per gripper one sensor (closer/NO) is required, optionally a cable extension.



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Electronic magnetic switches



1 Cable outlet

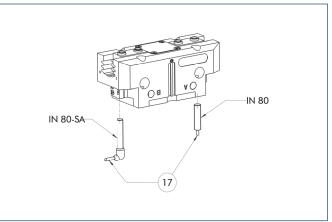
End position monitoring for mounting in the C-slot

Description	ID	Recommended product
Electronic magnetic switches		
MMS 22-S-M5-PNP	0301438	
MMS 22-S-M5-NPN	0301439	
MMS 22-S-M8-PNP	0301432	•
MMS 22-S-M8-NPN	0301433	
MMSK 22-S-PNP	0301434	
MMSK 22-S-NPN	0301435	
Electronic magnetic switches with	lateral cable outlet	
MMS 22-S-M5-PNP-SA	0301448	
MMS 22-S-M5-NPN-SA	0301449	
MMS 22-S-M8-PNP-SA	0301442	•
MMS 22-S-M8-NPN-SA	0301443	
MMSK 22-S-PNP-SA	0301444	
MMSK 22-S-NPN-SA	0301445	
Connection cables		
KA BG05-L 3P-0300	0301652	
KA BGO8-L 3P-0300-PNP	0301622	
KA BG08-L 3P-0500-PNP	0301623	
KA BW05-L 3P-0300	0301650	
KA BW08-L 3P-0300-NPN	0301602	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-NPN	9641116	
KA BW08-L 3P-0500-PNP	0301502	
Cable extensions		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	

Two sensors (closer/NO) are required for each gripper, plus extension cables as an option.

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

Inductive proximity switches



(17) Cable outlet

End position monitoring for direct mounting

Description	ID	Recommended product
Inductive proximity switches		
IN 80-S-M8	0301478	•
IN 80-S-M12	0301578	
INK 80-S	0301550	
Inductive proximity switch with la	teral outlet	
IN 80-S-M12-SA	0301587	
IN 80-S-M8-SA	0301483	•
INK 80-S-SA	0301566	
Connection cables		
KA BGO8-L 3P-0300-PNP	0301622	
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BWO8-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
Cable extensions		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	

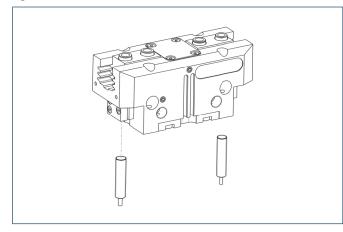
Two sensors (closer/NO) are required for each gripper, plus extension cables as an option.

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



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Cylindrical Reed Switches



End position monitoring mounted with mounting kit

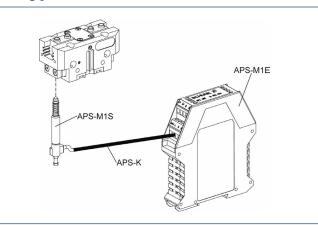
Description	ID
Mounting kit for proximity switch	
AS-RMS 80 PGN/PZN-plus 64/80	0377725
Reed Switches	
RMS 80-S-M8	0377721
(() () ()	

Two sensors (closer/NO) are required for each gripper, plus extension cables as an option.

(1) This mounting kit needs to be ordered optionally as an accessory.

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

Analog position sensor



Analog multi position monitoring for any desired positions

Description	ID
Mounting kit	
AS-APS-M1-64/1	0302075
AS-APS-M1-64/2	0302076
Connection cables	
APS-K0200	0302066
APS-K0700	0302068
Electronic Processor	
APS-M1E	0302064
Sensor	
APS-M1S	0302062

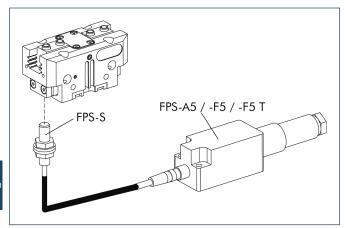
When using an APS system, for each gripper a mounting kit (AS-APS), an APS sensor (APS-M 1S, incl. 3 m cable) as well as an electronics (APS-M1e) are required.

An extension cable (APS-K) can be connected between the sensor and the electronics as an option. The max. cable length between the sensor and the electronics is 10 m, between the electronics and their control unit (PLC) it is max. 1 m.



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Flexible Position Sensor



Flexible position monitoring of up to five positions

Description	ID
Mounting kit for FPS	
AS-PGN/PZN-plus 64/1, PGN/PZN-plus 80/2	0301630
Electronic Processor	
FPS-F5	0301805
FPS-F5 T	0301807
Sensor	
FPS-S M8	0301704

(i) When using a FPS system, a FPS sensor (FPS-S) and a control unit (FPS-F5 / F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as options in the "Accessories" catalog section.

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.

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