## Pneumatic • 3-Finger Centric Gripper • Universal Gripper

m



**Sizes** 40 ... 300

Weight

0.13 kg ... 46 kg



**Gripping force** 255 N ... 35500 N



Stroke per finger 2 mm ... 35 mm



Workpiece weight 1.3 kg ... 127.5 kg

### **Application example**





Insertion tool for assembling small to mediumsized axles. Thanks to the rotary feed-through, the axles can be turned several times to an unlimited extent (> 360°). Slip ring contacts integrated in the rotary feed-through reliably supply the gripper with power.



2

3-Finger Centric Gripper PZN-plus

Rotary feed-through DDF



### Pneumatic • 3-Finger Centric Gripper • Universal Gripper

### **Universal Gripper**

universal Concentric Gripper with high gripping force and maximum moments thanks to multi-tooth guidance

### **Field of application**

Multi-purpose thanks to the diverse range of accessories. Can also be used in fields of application with special requirements to the gripper (temperature, chemical resistance, dirt, and many more).

### Your advantages and benefits

**Robust multi-tooth guidance** for precise handling

High maximum moments possible suitable for using long gripper fingers

Wedge-hook design for high power transmission and synchronized gripping

Air supply via hose-free direct connection or screw connections

for the flexible supply of compressed air in all automation systems

**Comprehensive sensor accessory program** for versatile interrogation possibilities and control of stroke position

#### **Manifold options**

for perfect adaption to your case of application (dust protection, high temperature, anti-corrosion and many more)



### General note to the series

Principle of function Wedge-hook kinematics

Housing material Aluminum alloy, hard-anodized

**Base jaw material** Steel

#### Actuation

pneumatic, with filtered compressed air (10 microns): dry, lubricated or non-lubricated Pressure medium: Required quality class of compressed air according to DIN ISO 8573-1: 6 4 4

### Warranty

36 months (details, general terms and conditions and operation manuals can be downloaded under www.schunk.com)

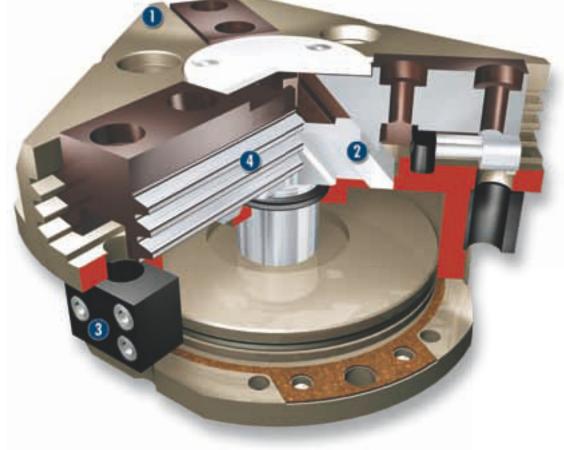
### Scope of delivery

Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly and operating manual with manufacturer's declaration



Pneumatic • 3-Finger Centric Gripper • Universal Gripper

### **Sectional diagram**





#### Housing

weight-optimized through application of hardanodized, high-strength aluminum alloy



## Wedge-hook design

for high power transmission and centric gripping



#### Sensor system

Brackets for proximity switches and adjustable control cams in the housing



### **Multiple-tooth guidance**

precise gripping through base jaw guidance with a high load capacity and a minimum play

## **Functional description**

The piston is moved up and down by compressed air. Through its angled active surfaces, the wedge hook transforms this movement into the lateral, synchronous gripping movement of both base jaws.

## **Options and special information**

**Dust-protection version** 

Absolutely sealed, increased degree of protection against the ingress of materials, for use in dusty environments

**Anti-corrosion version** for use in corrosion-inducing atmospheres

**High-temperature version** for use in hot environments

Force intensified version if higher gripping forces are required



## Pneumatic • 3-Finger Centric Gripper • Universal Gripper

### **Accessories**

Accessories from SCHUNK the suitable supplement for maximum functionality, reliability and performance of all automation modules.







#### **Universal intermediate** jaw

**Compensation unit** 







**Quick-change Jaw System** 



**Pressure maintenance** valve





Force measuring jaws Analog position sensor



**Flexible Position Sensor** 



(1) For the exact size of the required accessories, availability of this size and the designation and ID, please refer to the additional views at the end of the size in question. You will find more detailed information on our accessory range in the "Accessories" catalog section.

# General note to the series

### **Gripping force**

is the arithmetic total of the gripping force applied to each finger at distance P (see illustration) measured from the upper edge of the gripper.

#### **Finger length**

The finger length is measured from the upper edge of the gripper housing in the direction of the main axis.

### **Repeat accuracy**

is defined as the spread of the limit position after 100 consecutive strokes.

#### Workpiece weight

The recommended workpiece weight is calculated for a force-type connection with a coefficient of friction of 0.1 and a safety factor of 2 against slippage of the workpiece on acceleration due to gravity g. Considerably heavier workpiece weights are permitted with form-fit gripping.

### **Closing and opening times**

Closing and opening times are purely the times that the base jaws or fingers are in motion. Valve switching times, hose filling times or PLC reaction times are not included in the above times and must be taken into consideration when determining cycle times.







**Sensor cables** 

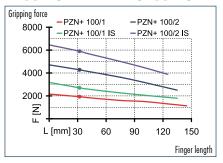
### **Sensor Distributor**



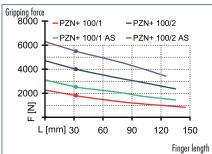
## Pneumatic • 3-Finger Centric Gripper • Universal Gripper



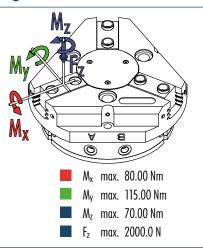
## Gripping force, I.D. gripping



## Gripping force, O.D. gripping



### **Finger load**



The indicated moments and forces are static values, apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may be reduced.

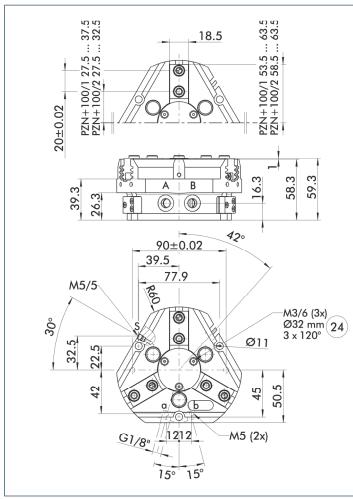
# **Technical data**

Description		PZN-plus 100-1		PZN-plus 100-1-AS		PZN-plus 100-1-IS	PZN-plus 100-2-IS
ID		0303312	0303412	0303512	0303612	0303542	0303642
Stroke per finger	[mm]	10	5	10	5	10	5
Closing force	[N]	1800	4000	2520	5500		
Opening force	[N]	1920	4280			2700	5900
Min. spring force	[N]			720	1500	780	1620
Weight	[kg]	1.41	1.41	1.95	1.95	1.95	1.95
Recommended workpiece weight	[kg]	9	20	9	20	9	20
Air consumption per double stroke	[cm <sup>3</sup> ]	120	120	210	210	210	210
Min./max. operating pressure	[bar]	2/8	2/8	4/6.5	4/6.5	4/6.5	4/6.5
Nominal operating pressure	[bar]	6	6	6	6	6	6
Closing/opening time	[s]	0.1/0.1	0.1/0.1	0.1/0.2	0.1/0.2	0.2/0.1	0.2/0.1
Max. permitted finger length	[mm]	145	135	135	125	135	125
Max. permitted weight per finger	[kg]	1.1	1.1	1.1	1.1	1.1	1.1
IP class		40	40	40	40	40	40
Min./max. ambient temperature	[°C]	-10/90	-10/90	-10/90	-10/90	-10/90	-10/90
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
Cleanroom class		5	5	5	5	5	5
ISO-classification 14644-1		J	J	J	J	J	J
<b>OPTIONS and their charact</b>	eristics						
Dust-protection version		37303312	37303412	37303512	37303612	37303542	37303642
IP class		64	64	64	64	64	64
Weight	[kg]	1.9	1.9	2.44	2.44	2.44	2.44
Anti-corrosion version		38303312	38303412	38303512	38303612	38303542	38303642
High-temperature version		39303312	39303412	39303512	39303612	39303542	39303642
Min./max. ambient temperature	[°[]	-10/130	-10/130	-10/130	-10/130	-10/130	-10/130
Force intensified version		PZN-plus 100-1-	PZN-plus 100-2-	PZN-plus 100-1-		PZN-plus 100-1-	
		KVZ	KVZ	AS-KVZ		IS-KVZ	
ID		0372203	0372213	0372223		0372243	
Closing force	[N]	3240	7200	3960			
Opening force	[N]	3455	7705			4235	
Weight	[kg]	2.3	2.3	2.7		2.7	
Maximum pressure	[bar]	8	8	6		6	
Max. permitted finger length	[mm]	100	80	80		80	
Precision version		0303342	0303442	0303492	0303592		



### Pneumatic • 3-Finger Centric Gripper • Universal Gripper

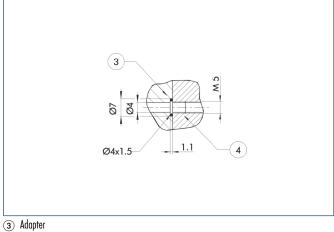
## **Main view**



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

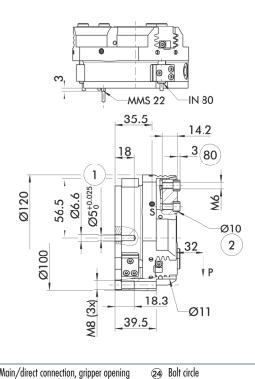
(1) The SDV-P pressure maintenance valve can also be used for I.D. or O.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see "Accessories" catalog section).

### **Hose-free direct connection**



(4) Gripper

The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.





## A, a Main/direct connection, gripper opening

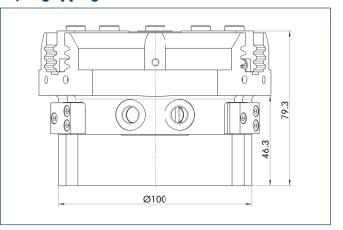
- B, b Main/direct connection, gripper closing S
  - Air purge connection
- Gripper connection (1)

(2) Finger connection

80 Depth of the centering sleeve hole in the

matching part

## AS/IS gripping force maintenance device

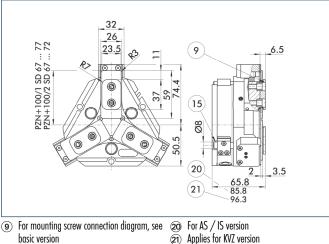


The mechanical gripping force maintenance device ensures a minimum gripping force even in case of pressure drop. This acts as closing force in the AS version, and as opening force in the IS version. In addition, the gripping force maintenance device can also be used for increasing the gripping force or for single-acting gripping.



### Pneumatic • 3-Finger Centric Gripper • Universal Gripper

### **Dust-protection version**

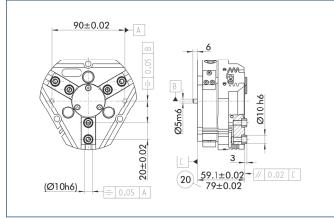


(21) Applies for KVZ version

Sealing bolt (15)

The "dust-protection" option increases the degree of protection against penetrating substances. The screw connection diagram shifts by the height of the intermediate jaw. The finger length is still measured from the upper edge of the gripper housing.

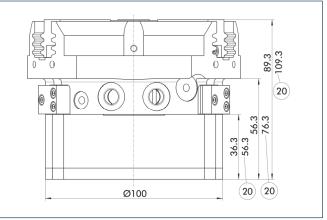
## **Precision version**



### 20 For AS / IS version

The indicated tolerances just refer to the types of precision versions shown in the chart of technical specifications. All other types of precision versions are available on request.

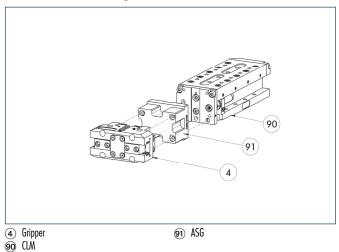
## **Force intensified version**



### (20) For AS / IS version

The KVZ cylinder increases the gripping forces during opening and closing. A second, in series-connected piston also increases the force on the wedge hook. The full gripping force shown in the data table is sometimes only reached after a few hundred gripping cycles. Please consider that grippers which are equipped with a gripping force maintenance device (AS / IS) are higher.

## **Modular Assembly Automation**

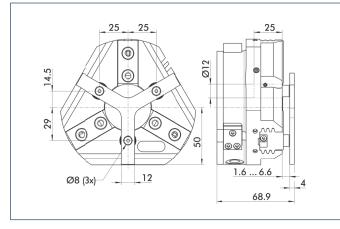


This gripper can be combined with the standard linear modules LM, KLM, CLM and ELM of the GEMOTEC modular system. For more information see our main catalog "Modular Assembly Automation".



### Pneumatic • 3-Finger Centric Gripper • Universal Gripper

## Spring-loaded pressure piece

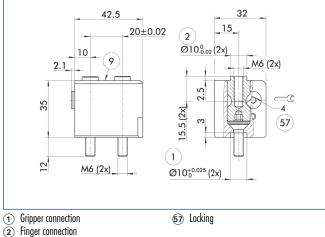


For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke	Min. force
Spring-loaded pressure piece			
A-PZN-plus/DPZ-plus 100	0303722	5 mm	35 N

The pressure piece cannot be combined with the dust-protection version. Please contact us if you require a special pressure piece.

### **Quick-change Jaw System**



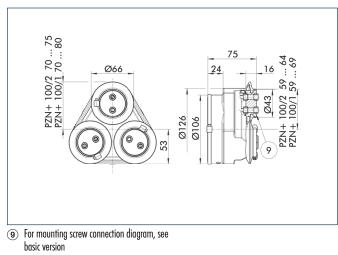
 For mounting screw connection diagram, see basic version

The BSWS quick-change jaw system enables top jaws to be changed on the gripper manually and rapidly. An adapter (BSWS-A) and a base (BSWS-B) are required for each gripper jaw.

For a reverse assembly without height set-up, one adapter (BSWS-A) and a kit (BSWS-U) per gripper jaw are required. Another effect of the BSWS-U is, that there are no disturbing fastening bores in the finger contour.

Description	ID
Quick-change Jaw System adapte	76
BSWS-A 100	0303026
Quick-change Jaw System base	
BSWS-B 100	0303027
Quick-change Jaw System reverse	ed
BSWS-U 100	0303043

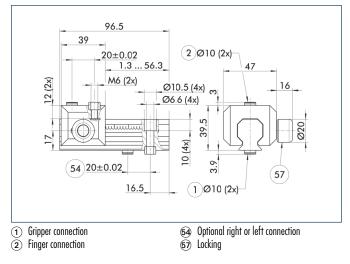
### **Protection cover**



The HUE protective cover completely protects the gripper against external influences up to IP65 if an additional sealing of the cover bottom is provided as part of the application. The mounting diagram shifts by the height of the intermediate jaw.

Description	ID	Cleanroom class ISO-classification 14644-1
Protection cover		
HUE PZN-plus 100	0303482	2

## Universal intermediate jaw



The universal intermediate jaw allows fast tool-free and reliable plugging and shifting of top jaws at the gripper.

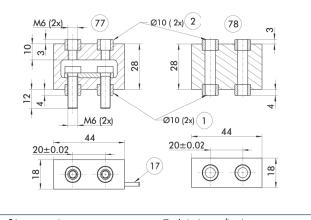
Description	ID	Grid dimension
Universal intermediate jaw		
UZB 100	0300044	2.5 mm
UZB-S 100	5518272	2.5 mm

The slide UZB-S can be removed completely and has to be ordered separately. Moreover, it allows a fast jaw change.



## Pneumatic • 3-Finger Centric Gripper • Universal Gripper

## Force measuring jaws





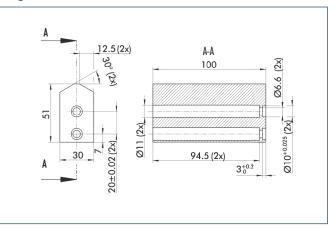
Gripper connection
Finger connection
Cable outlet

Active intermediate jawsPassive intermediate jaws

Force measuring jaws measure gripping forces, but can also determine workpiece weights or dimensional deviations. There are active and passive intermediate jaws (FMS-ZBA or FMS-ZBP). At least one active force measuring jaw is required per gripper, the rest can be passive. For each active jaw, a FMS-A1 control unit and a FMS-A connection cable are required.

Description	ID
Active intermediate jaws	
FMS-ZBA 100	0301836
Passive intermediate jaws	
FMS-ZBP 100	0301837
Electronic Processor	
FMS-A1	0301810
Connection cables	
FMS-AK0200	0301820
FMS-AK0500	0301821
FMS-AK1000	0301822
FMS-AK2000	0301823

## **Finger blanks**



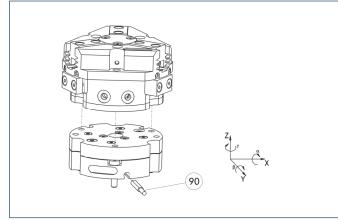
Finger blanks for customized subsequent machining

Description	ID	Material	Scope of delivery
Finger blanks			
ABR-plus 100	0300012	Aluminum	1
SBR-plus 100	0300022	16 MnCr 5	1



### Pneumatic • 3-Finger Centric Gripper • Universal Gripper

### **Tolerance compensation unit**

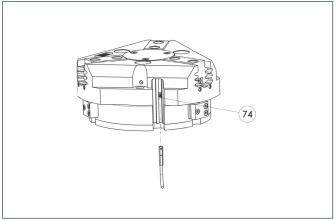


90 Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details see catalog "Robot Accessories".

Description	ID	Locking	Deflection
Compensation unit			
TCU-100-2-MV-Z	0324794	Yes	
TCU-100-2-0V-Z	0324799	No	

# Programmable magnetic switch



(74) Stop for MMS-P

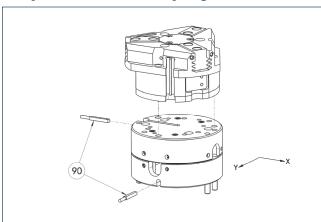
Position monitoring with two programmable positions per sensor. The end position monitoring is mounted in the C-slot.

Description	ID	Recommended product
Programmable magnetic switch		
MMS-P 22-S-M8-PNP	0301370	•
MMSK-P 22-S-PNP	0301371	
Connection cables		
KA BG08-L 4P-0500	0307767	
KA BG08-L 4P-1000	0307768	
KA BW08-L 4P-0500	0307765	
KA BW08-L 4P-1000	0307766	
Sensor Distributor		
V2-M8-4P-2XM8-3P	0301380	

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

① Per gripper one sensor (closer/NO) is required, optionally a cable extension.

## **Compensation unit with spring reset**



### 90 Monitoring

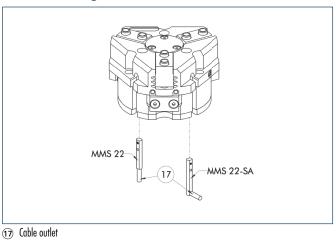
Grippers can be directly mounted without using an adapter plate. For details see our catalog "Robot Accessories".

Description	ID	Compensation travel	Reset force
Compensation unit			
AGE-F-XY-080-1	0324960	±5 mm	28.3 N
AGE-F-XY-080-2	0324961	±5 mm	42.5 N
AGE-F-XY-080-3	0324962	±5 mm	47.6 N



## Pneumatic • 3-Finger Centric Gripper • Universal Gripper

## **Electronic magnetic switches**

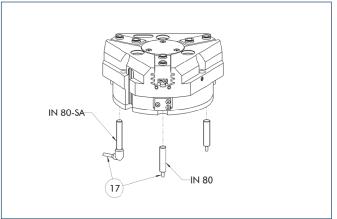


# 4

End position monitoring for mounting in the C-slot

Description	ID	Recommended product
Electronic magnetic switches		
MMS 22-S-M5-PNP	0301438	
MMS 22-S-M5-NPN	0301439	
MMS 22-S-M8-PNP	0301432	•
MMS 22-S-M8-NPN	0301433	
MMSK 22-S-PNP	0301434	
MMSK 22-S-NPN	0301435	
Electronic magnetic switches with	n lateral cable outlet	
MMS 22-S-M5-PNP-SA	0301448	
MMS 22-S-M5-NPN-SA	0301449	
MMS 22-S-M8-PNP-SA	0301442	•
MMS 22-S-M8-NPN-SA	0301443	
MMSK 22-S-PNP-SA	0301444	
MMSK 22-S-NPN-SA	0301445	
Reed Switches		
RMS 22-S-M8	0377720	•
Connection cables		
KA BG05-L 3P-0300	0301652	
KA BGO8-L 3P-0300-PNP	0301622	
KA BG08-L 3P-0500-PNP	0301623	
KA BW05-L 3P-0300	0301650	
KA BW08-L 3P-0300-NPN	0301602	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-NPN	9641116	
KA BW08-L 3P-0500-PNP	0301502	
Cable extensions		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	

## Inductive proximity switches



#### (17) Cable outlet

End position monitoring for direct mounting

Description	ID	Recommended product
Inductive proximity switches		
IN 80-S-M8	0301478	•
IN 80-S-M12	0301578	
INK 80-S	0301550	
Inductive proximity switch with lo	iteral outlet	
IN 80-S-M12-SA	0301587	
IN 80-S-M8-SA	0301483	•
INK 80-S-SA	0301566	
Connection cables		
KA BGO8-L 3P-0300-PNP	0301622	
KA BGO8-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
Cable extensions		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	

Two sensors (closer/NO) are required for each gripper, plus extension cables as an option.

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

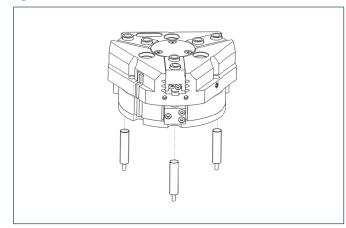
Two sensors (closer/NO) are required for each gripper, plus extension cables as an option.

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



### Pneumatic • 3-Finger Centric Gripper • Universal Gripper

## **Cylindrical Reed Switches**



End position monitoring mounted with mounting kit

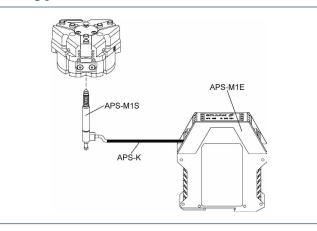
Description	ID
Mounting kit for proximity switch	
AS-RMS 80 PGN/PZN-plus 100/125	0377726
Reed Switches	
RMS 80-S-M8	0377721
() ()-	

Two sensors (closer/NO) are required for each gripper, plus extension cables as an option.

(1) This mounting kit needs to be ordered optionally as an accessory.

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

### **Analog position sensor**



Analog multi position monitoring for any desired positions

Description	ID
Mounting kit	
AS-APS-M1-100/1	0302079
AS-APS-M1-100/2	0302080
Connection cables	
APS-K0200	0302066
APS-K0700	0302068
Electronic Processor	
APS-M1E	0302064
Sensor	
APS-M1S	0302062

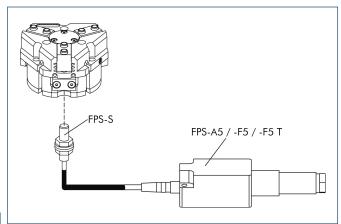
When using an APS system, for each gripper a mounting kit (AS-APS), an APS sensor (APS-M 1S, incl. 3 m cable) as well as an electronics (APS-M1e) are required.

① An extension cable (APS-K) can be connected between the sensor and the electronics as an option. The max. cable length between the sensor and the electronics is 10 m, between the electronics and their control unit (PLC) it is max. 1 m.



## Pneumatic • 3-Finger Centric Gripper • Universal Gripper

## **Flexible Position Sensor**



Flexible position monitoring of up to five positions

Description	ID
Mounting kit for FPS	
AS-PGN/PZN-plus 100/1	0301634
AS-PGN/PZN-plus 100/2, PZB 125	0301635
Electronic Processor	
FPS-F5	0301805
FPS-F5 T	0301807
Sensor	
FPS-S M8	0301704

When using a FPS system, a FPS sensor (FPS-S) and a control unit (FPS-F5 / F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as options in the "Accessories" catalog section.

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.

H

