Pneumatic • 3-Finger Centric Gripper • Universal Gripper

m



Sizes 40 ... 300

Weight

0.13 kg ... 46 kg



Gripping force 255 N ... 35500 N



Stroke per finger 2 mm ... 35 mm



Workpiece weight 1.3 kg ... 127.5 kg

Application example





Insertion tool for assembling small to mediumsized axles. Thanks to the rotary feed-through, the axles can be turned several times to an unlimited extent (> 360°). Slip ring contacts integrated in the rotary feed-through reliably supply the gripper with power.



2

3-Finger Centric Gripper PZN-plus

Rotary feed-through DDF



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Universal Gripper

universal Concentric Gripper with high gripping force and maximum moments thanks to multi-tooth guidance

Field of application

Multi-purpose thanks to the diverse range of accessories. Can also be used in fields of application with special requirements to the gripper (temperature, chemical resistance, dirt, and many more).

Your advantages and benefits

Robust multi-tooth guidance for precise handling

High maximum moments possible suitable for using long gripper fingers

Wedge-hook design for high power transmission and synchronized gripping

Air supply via hose-free direct connection or screw connections

for the flexible supply of compressed air in all automation systems

Comprehensive sensor accessory program for versatile interrogation possibilities and control of stroke position

Manifold options

for perfect adaption to your case of application (dust protection, high temperature, anti-corrosion and many more)



General note to the series

Principle of function Wedge-hook kinematics

Housing material Aluminum alloy, hard-anodized

Base jaw material Steel

Actuation

pneumatic, with filtered compressed air (10 microns): dry, lubricated or non-lubricated Pressure medium: Required quality class of compressed air according to DIN ISO 8573-1: 6 4 4

Warranty

36 months (details, general terms and conditions and operation manuals can be downloaded under www.schunk.com)

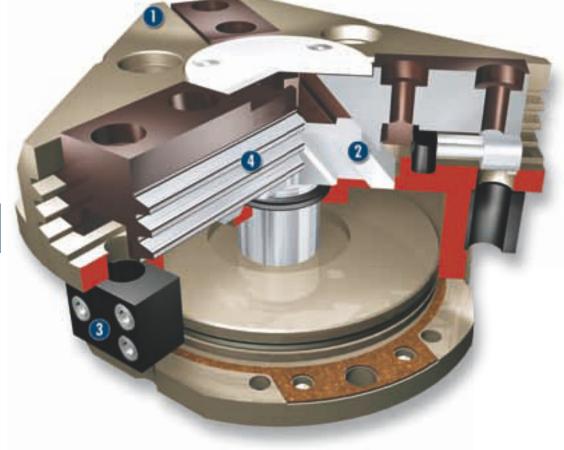
Scope of delivery

Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly and operating manual with manufacturer's declaration



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Sectional diagram





D Housing

weight-optimized through application of hardanodized, high-strength aluminum alloy

2

Wedge-hook design for high power transmission and centric

gripping



Brackets for proximity switches and adjustable control cams in the housing



Multiple-tooth guidance

precise gripping through base jaw guidance with a high load capacity and a minimum play

Functional description

The piston is moved up and down by compressed air. Through its angled active surfaces, the wedge hook transforms this movement into the lateral, synchronous gripping movement of both base jaws.

Options and special information

Dust-protection version

Absolutely sealed, increased degree of protection against the ingress of materials, for use in dusty environments

Anti-corrosion version for use in corrosion-inducing atmospheres

High-temperature version for use in hot environments

Force intensified version if higher gripping forces are required



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Accessories

Accessories from SCHUNK the suitable supplement for maximum functionality, reliability and performance of all automation modules.







Universal intermediate jaw

Compensation unit







Quick-change Jaw System



Pressure maintenance valve





Force measuring jaws

Analog position sensor



Flexible Position Sensor



(1) For the exact size of the required accessories, availability of this size and the designation and ID, please refer to the additional views at the end of the size in question. You will find more detailed information on our accessory range in the "Accessories" catalog section.

General note to the series

Gripping force

is the arithmetic total of the gripping force applied to each finger at distance P (see illustration) measured from the upper edge of the gripper.

Finger length

The finger length is measured from the upper edge of the gripper housing in the direction of the main axis.

Repeat accuracy

is defined as the spread of the limit position after 100 consecutive strokes.

Workpiece weight

The recommended workpiece weight is calculated for a force-type connection with a coefficient of friction of 0.1 and a safety factor of 2 against slippage of the workpiece on acceleration due to gravity g. Considerably heavier workpiece weights are permitted with form-fit gripping.

Closing and opening times

Closing and opening times are purely the times that the base jaws or fingers are in motion. Valve switching times, hose filling times or PLC reaction times are not included in the above times and must be taken into consideration when determining cycle times.







Sensor cables

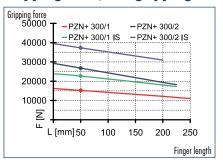
Sensor Distributor



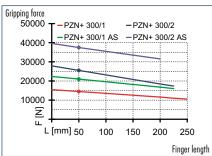
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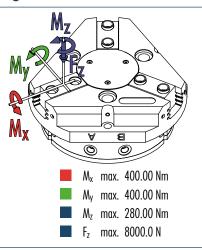
Gripping force, I.D. gripping



Gripping force, O.D. gripping



Finger load



The indicated moments and forces are static values, apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may be reduced.

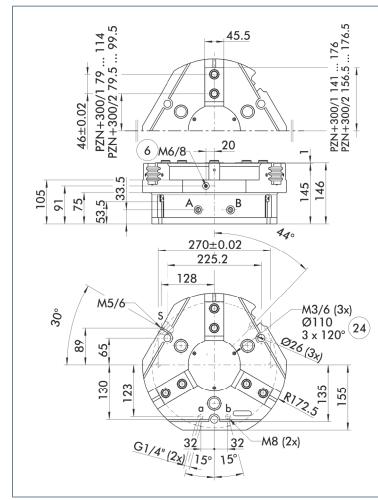
Technical data

Description		PZN-plus 300-1	PZN-plus 300-2	PZN-plus 300-1-AS	PZN-plus 300-2-AS	PZN-plus 300-1-IS	PZN-plus 300-2-IS
ID		0303317	0303417	0303517	0303617	0303547	0303647
Stroke per finger	[mm]	35	20	35	20	35	20
Closing force	[N]	14500	25500	21000	35500		
Opening force	[N]	15200	16800			22700	37300
Min. spring force	[N]			6500	10000	7500	10500
Weight	[kg]	33	33	43.5	43.5	43.5	43.5
Recommended workpiece weight	[kg]	72.5	127.5	72.5	127.5	72.5	127.5
Air consumption per double stroke	[cm ³]	2850	2850	5050	5050	5050	5050
Min./max. operating pressure	[bar]	2/8	2/8	4/6.5	4/6.5	4/6.5	4/6.5
Nominal operating pressure	[bar]	6	6	6	6	6	6
Closing/opening time	[s]	1.3/1.3	1.3/1.3	1.2/2.5	1.2/2.5	2/1.2	2/1.2
Max. permitted finger length	[mm]	250	225	225	200	225	200
Max. permitted weight per finger	[kg]	11.5	11.5	11.5	11.5	11.5	11.5
IP class		40	40	40	40	40	40
Min./max. ambient temperature	[°(]	-10/90	-10/90	-10/90	-10/90	-10/90	-10/90
Repeat accuracy	[mm]	0.05	0.05	0.05	0.05	0.05	0.05
Cleanroom class		5	5	5	5	5	5
ISO-classification 14644-1		J	J	J	J	J	J
OPTIONS and their charac	teristics						
Dust-protection version		37303317	37303417	37303517	37303617	37303547	37303647
IP class		64	64	64	64	64	64
Weight	[kg]	35.5	35.5	46	46	46	46
Anti-corrosion version		38303317	38303417	38303517	38303617	38303547	38303647
High-temperature version		39303317	39303417	39303517	39303617	39303547	39303647
Min./max. ambient temperature	[°(]	-10/130	-10/130	-10/130	-10/130	-10/130	-10/130
Precision version		0303347	0303447	0303497	0303597		



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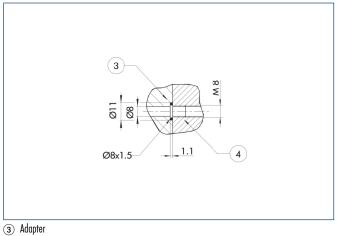
Main view



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

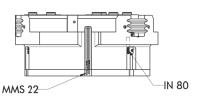
(1) The SDV-P pressure maintenance valve can also be used for I.D. or O.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see "Accessories" catalog section).

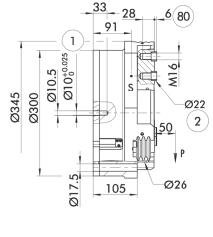
Hose-free direct connection



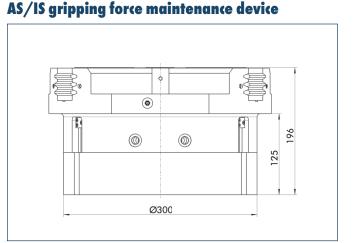
(4) Gripper

The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.





A, a Main/direct connection, gripper opening (6) Lubricating nipple connection B, b Main/direct connection, gripper closing Bolt circle 24) Depth of the centering sleeve hole in the 80 matching part



The mechanical gripping force maintenance device ensures a minimum gripping force even in case of pressure drop. This acts as closing force in the AS version, and as opening force in the IS version. In addition, the gripping force maintenance device can also be used for increasing the gripping force or for single-acting gripping.



S

(1)

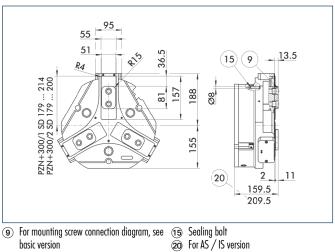
Air purge connection

Gripper connection

(2) Finger connection

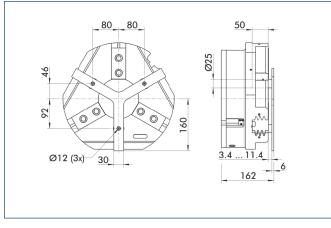
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Dust-protection version



The "dust-protection" option increases the degree of protection against penetrating substances. The screw connection diagram shifts by the height of the intermediate jaw. The finger length is still measured from the upper edge of the gripper housing.

Spring-loaded pressure piece

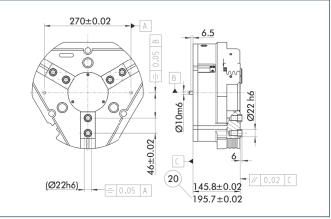


For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke	Min. force
Spring-loaded pressure piece			
A-PZN-plus/DPZ-plus 300	0303727	8 mm	160 N

The pressure piece cannot be combined with the dust-protection version. Please contact us if you require a special pressure piece.

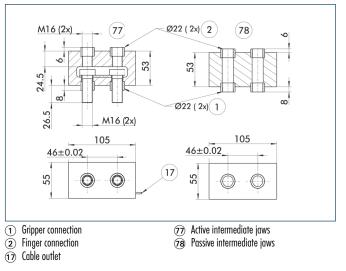
Precision version



20 For AS / IS version

The indicated tolerances just refer to the types of precision versions shown in the chart of technical specifications. All other types of precision versions are available on request.

Force measuring jaws



Force measuring jaws measure gripping forces, but can also determine workpiece weights or dimensional deviations. There are active and passive intermediate jaws (FMS-ZBA or FMS-ZBP). At least one active force measuring jaw is required per gripper, the rest can be passive. For each active jaw, a FMS-A1 control unit and a FMS-A connection cable are required.

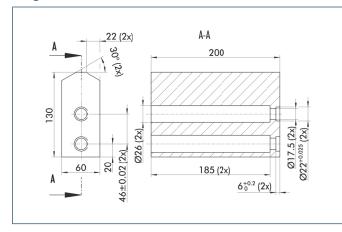
Description	ID
Active intermediate jaws	
FMS-ZBA 300	0301846
Passive intermediate jaws	
FMS-ZBP 300	0301847
Electronic Processor	
FMS-A2	0301811
Connection cables	
FMS-AK0200	0301820
FMS-AK0500	0301821
FMS-AK1000	0301822
FMS-AK2000	0301823

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.



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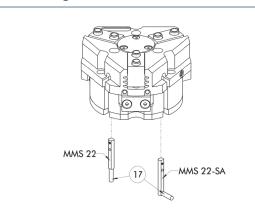
Finger blanks



Finger blanks for customized subsequent machining

Description	ID	Material	Scope of delivery
Finger blanks			
ABR-plus 300	0300016	Aluminum	1
SBR-plus 300	0300026	16 MnCr 5	1

Electronic magnetic switches



(17) Cable outlet

End position monitoring for mounting in the C-slot

1 0	0	
Description	ID	Recommended product
Electronic magnetic switches		
MMS 22-S-M5-PNP	0301438	
MMS 22-S-M5-NPN	0301439	
MMS 22-S-M8-PNP	0301432	•
MMS 22-S-M8-NPN	0301433	
MMSK 22-S-PNP	0301434	
MMSK 22-S-NPN	0301435	
Electronic magnetic switches with	lateral cable outlet	
MMS 22-S-M5-PNP-SA	0301448	
MMS 22-S-M5-NPN-SA	0301449	
MMS 22-S-M8-PNP-SA	0301442	•
MMS 22-S-M8-NPN-SA	0301443	
MMSK 22-S-PNP-SA	0301444	
MMSK 22-S-NPN-SA	0301445	
Reed Switches		
RMS 22-S-M8	0377720	•
Connection cables		
KA BG05-L 3P-0300	0301652	
KA BGO8-L 3P-0300-PNP	0301622	
KA BGO8-L 3P-0500-PNP	0301623	
KA BW05-L 3P-0300	0301650	
KA BW08-L 3P-0300-NPN	0301602	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-NPN	9641116	
KA BW08-L 3P-0500-PNP	0301502	
Cable extensions		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
		1

Two sensors (closer/NO) are required for each gripper, plus extension cables as an option.

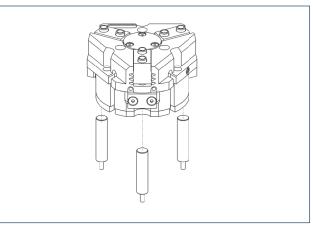
Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.



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Inductive proximity switches



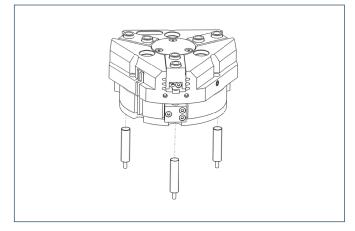
End position monitoring for direct mounting

Description	ID	Recommended product
Inductive proximity switches		
IN 80-S-M8	0301478	•
IN 80-S-M12	0301578	
INK 80-S	0301550	
Connection cables		
KA BGO8-L 3P-0300-PNP	0301622	
KA BGO8-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BWO8-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
Cable extensions		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	

Two sensors (closer/NO) are required for each gripper, plus extension cables as an option.

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

Cylindrical Reed Switches



End position monitoring mounted with mounting kit

Description	ID
Mounting kit for proximity switch	
AS-RMS 80 PGN/PZN-plus 160-380	0377727
Reed Switches	
RMS 80-S-M8	0377721
	• 16 1 • 1 • • 11

Two sensors (closer/NO) are required for each gripper, plus extension cables as an option.

(1) This mounting kit needs to be ordered optionally as an accessory.

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.





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APS-M1E APS-M1S APS-K o

Analog position sensor

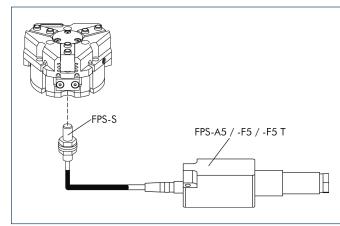
Analog multi position monitoring for any desired positions

Description	ID
Mounting kit	
AS-APS-M1-300/1	0302088
AS-APS-M1-300/2	0302089
Connection cables	
APS-K0200	0302066
APS-K0700	0302068
Electronic Processor	
APS-M1E	0302064
Sensor	
APS-M1S	0302062

When using an APS system, for each gripper a mounting kit (AS-APS), an APS sensor (APS-M 1S, incl. 3 m cable) as well as an electronics (APS-M1e) are required.

① An extension cable (APS-K) can be connected between the sensor and the electronics as an option. The max. cable length between the sensor and the electronics is 10 m, between the electronics and their control unit (PLC) it is max. 1 m.

Flexible Position Sensor



Flexible position monitoring of up to five positions

ID
0301642
0301805
0301807
0301704

When using a FPS system, a FPS sensor (FPS-S) and a control unit (FPS-F5 / F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as options in the "Accessories" catalog section.

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.

